# Robust Predictions for DSGE Models with Incomplete Information<sup>\*</sup>

Ryan ChahrourRobert UlbrichtBoston CollegeBoston College

June 10, 2021

#### Abstract

We provide predictions for DSGE models with incomplete information that are robust across information structures. Our approach maps an incomplete-information model into a full-information economy with time-varying expectation wedges and provides conditions that ensure the wedges are rationalizable by some information structure. Using our approach, we quantify the potential importance of information as a source of business cycle uctuations in an otherwise frictionless model. Our approach uncovers a central role for rm-speci c demand shocks in supporting aggregate con dence uctuations. Only if rms face unobserved local demand shocks can con dence uctuations account for a signi cant portion of the US business cycle.

**Keywords:** Business cycles, DSGE models, incomplete-information, information-robust predictions.

JEL Classi cation: E32, D84.

<sup>\*</sup>We thank our discussants Guillaume Chevillon, Stephane Dupraz, Alexandre Kohlhas, Jianjun Miao and Anna Orlik for many valuable comments. Ulbricht gratefully acknowledges nancial support from the European Union's Horizon 2020 Program under grant agreement No. 649396. *Email addresses:* ryan.chahrour@bc.edu, ulbricht@bc.edu.

# 1 Introduction

What are the sources of aggregate uctuations? One common view is that business cycles are caused by shocks to the con dence of consumers and rms. The literature on business cycles has formalized this view in several ways, including modeling con dence uctuations as a consequence of incomplete information (e.g., Lorenzoni, 2009; Angeletos and La'O, 2013; Benhabib, Wang and Wen, 2015). Yet, relatively few of these information-based models have been investigated quantitatively. At least in part, this is because the private information structures governing people's beliefs are hard to observe in the data or | as argued by Sims (2003) and Woodford (2003) | may have no observable counterpart.

In this paper, we quantify the potential importance of con dence-driven business cycles using a novel approach that bypasses the challenge of postulating ad-hoc information structures. The approach takes the *economic environment* (technology, preferences, market structure) as given, but does not require a complete speci cation of the *information structure* that governs people's beliefs. Instead, we provide an \information-robust" characterization of all equilibria that are possible within a given economic environment.

Methodological contribution We develop our methodology for a canonical class of models with dispersed or incomplete information, without any restriction on the set of signals governing people's beliefs regarding their own idiosyncratic shocks, the aggregate state of the economy, what other agents believe, and so on. Notably, our general framework encompasses virtually all linear rational expectations DSGE models explored in the literature. We show how to map these models into a \primal" economy, in which all agents have full information and where deviations from full information are summarized by exogenous wedges in agents' equilibrium expectations. We then develop necessary and su cient conditions for the existence of an information structure that is consistent with the expectation errors captured by these wedges. Subject to these conditions, the primal economy is isomorphic to the incomplete-information economy.

Exploiting this equivalence, we derive a complete characterization of all information equilibria within a given economic environment. Speci cally, our characterization allows the researcher to specify a (possibly empty) *minimal information set* re ecting their prior of what constitutes a lower bound on agents' information. Our main theorem then states that an equilibrium of the primal economy corresponds to an equilibrium of the information economy if and only if the expectation errors captured by the exogenous wedges are orthogonal to the corresponding agent's actions and each element of that agent's minimal information set. In our applications, we show how to use this characterization to draw concrete economic conclusions about equilibrium in the incomplete information model, without ever completely specifying the information available to agents.

**Applied contribution** To demonstrate the usefulness of our approach, we use it to ask: *Under what conditions* can changes in con dence generate sizable uctuations in aggregate economic activity? As an illustration, we rst examine this question in the context of a simple price-setting model similar to the one in Woodford (2003). The model describes the problem of price-setting rms who face exogenous aggregate demand and downward-sloping individual demand functions. Applied to this model, our methodology can be used to analytically bound the variances of endogenous variables, to sign cross-covariances among them, and to limit their autocorrelations. Among our results, we nd that any information structure that allows rms to contemporaneously observe their own sales implies that aggregate in ation must be procyclical. Moreover, if either idiosyncratic or aggregate demand is observed (or constant), then aggregate output does not uctuate.

After demonstrating our approach in this simple context, we then use it to explore the potential for con dence-driven business cycles quantitatively. Our quantitative model is a exible price business cycle model without capital, in which households and rms live on informationally disparate \islands." The inclusion of households introduces the potential for additional aggregate demand channels that act through incomplete information. Like the price-setting example, rms on each island experience uctuations in local demand. In addition, we allow for exogenous uctuations in aggregate productivity, as well as temporary and persistent changes in rm-level productivity.

Whether the model generates aggregate uctuations beyond those induced by aggregate productivity shocks depends on its ability to generate expectation errors that are correlated in the cross-section. There are two potential sources of such correlation. First, agents can be jointly optimistic or pessimistic regarding the aggregate state of productivity, as in Lorenzoni (2009) or Angeletos and La'O (2010). Second, agents can be jointly optimistic or pessimistic about their own idiosyncratic conditions, as in Angeletos and La'O (2013) or Benhabib, Wang and Wen (2015), possibly accentuated by strategic uncertainty. Both channels are disciplined by the properties of the fundamental shocks to productivity and demand. Our approach allows us to provide a general characterization of these restrictions that does not hinge on speci c structural assumptions about people's information.

For reference, we rst establish a novel theoretical benchmark for the case in which the stochastic process governing idiosyncratic shocks is *unrestricted* by data. For this case, we show that con dence-driven uctuations can in principle generate *any* autocovarince struc-

ture for output and in ation, bypassing all cross-equation restrictions that obtain under full information, provided that agents do not perfectly observe demand for their local goods when making production choices. This result extends ndings of Angeletos and La'O (2013) and Benhabib, Wang and Wen (2015) that correlated information shocks can generate arbitrary macroeconomic volatility if idiosyncratic shocks are su ciently volatile.

In light of this benchmark, we next ask: How much expectations-driven volatility can one generate for a realistic calibration of idiosyncratic shocks? We explore this question by calibrating the processes for idiosyncratic productivity and demand using existing micro-data estimates (Foster, Haltiwanger and Syverson, 2008). We then compute global upper bounds on con dence-induced output uctuations, their persistence, and the contemporaneous correlation with in ation.

For an empirically plausible calibration, we nd that the volatility-frontier for con denceinduced output uctuations is hump-shaped in aggregate persistence and is decreasing in the contemporaneous correlation with in ation. For an aggregate persistence and in ationcyclicality consistent with U.S. data, the maximal one-step-ahead volatility of con denceinduced uctuations in output is 0.011 (approximately 90 percent of its empirical counterpart). We demonstrate that the ability to generate sizable macro-volatility through con dence- uctuations hinges critically on the volatility of micro-shocks to rm demand. By contrast, micro-shocks to productivity play a somewhat dispensable role for generating aggregate volatility.

Why does idiosyncratic product demand play such an important role in supporting ag-

ported by uncertainty about productivity in this case are not nearly as large as those that can be generated by uncertainty regarding local demand. Across the cases we investigate, local demand uncertainty remains the most important prerequisite for large information-driven uctuations.

Finally, we explore the degree to which con dence-driven uctuations are consistent with U.S. business cycle data. To this end, we estimate a prototype wedge-economy similar to the one in Chari, Kehoe and McGrattan (2007), which captures the auto-covariance structure of the U.S. business cycle by construction. We then use our theoretical results to partition the estimated wedges into an informational component, which can be microfounded through incomplete information, and a non-informational residual. We nd that, in principle, con dence- uctuations can account for a large portion of the U.S. business cycle that remains unexplained after conditioning on productivity shocks.

Again, a prerequisite for such con dence- uctuations to be sizable is that rms do not know their idiosyncratic product demands while making their production plans: If local demand is perfectly observed, at most 3 percent of observed output uctuations can be accounted for by any type of con dence (regardless of what else rms observe). By contrast, if local demand is not observed but aggregate productivity is, up to 51 percent of output uctuations can be explained by correlated con dence regarding local conditions, leading us to conclude that local demand shocks are crucial for the model to support aggregate sentiment uctuations.

**Related literature** The methodology developed in this paper is related to Bergemann and Morris (2013, 2016) and Bergemann, Heumann and Morris (2014). These papers demonstrate the equivalence between *Bayes equilibria* in games with incomplete information and *Bayes correlated equilibria*. The approach developed in this paper is similar in that it also demonstrates the equivalence between a class of incomplete-information models with another class of full-information models. Our approach is signi cantly more general, however, because it is not limited to static game environments, but also applies to dynamic market economies, which is crucial for the application to business cycles. Closely related to our application to

# 2 Information-Robust Characterization

We present our main result in the context of a general linear rational expectations model with incomplete information. The framework encompasses virtually all linearized DSGE models used in the literature as well as the class of coordination games studied by Morris and Shin (2002) and others. After stating our main characterization theorem, we demonstrate its application in a simple model of price setting. In the subsequent sections, we apply our methodology to a quantitative business cycle model, and use it to explore the potential importance of con dence-driven business cycles in the United States.

#### 2.1 Main Theorem

**Framework** Consider a linear economy characterized by a system of expectational difference equations, in which date-*t* expectations are formed conditional on a collection of information sets  $f/_{i,t}^{j}g$ . Here,  $j \ge f_{0;1;:::;}Jg$  indexes a collection of ex-ante heterogeneous information classes that may di er arbitrarily. Within each class *j*, there is a continuum of ex-ante symmetric information sets, indexed by  $i \ge [0;1]$ , which may only di er in their ex-post realization of shocks.<sup>3</sup> We normalize j = 0 to refer to the full information set,  $/_{t}$ , which is de ned by the history of all variables that are realized at date t.<sup>4</sup>

Let  $g_{i;t}$  [ $g_{i;t}; g_t^a$ ], where  $g_{i;t}$  denotes a  $n \underset{0}{\overset{R}{\overset{1}{\overset{1}}{\overset{1}{\overset{1}}{\overset{1}{\overset{1}}{\overset{1}}{\overset{1}{\overset{1}}{\overset{1}}{\overset{1}}{\overset{1}{\overset{1}}{\overset{1}}{\overset{1}{\overset{1}}{\overset{1}{\overset{1}}{\overset{1}}{\overset{1}{\overset{1}}{\overset{1}}{\overset{1}}{\overset{1}{\overset{1}}$ 

We suppose that  $g_{i,t}$  satis es the following system of expectational di erence equations:

$$0 = \bigvee_{j=0}^{\mathcal{H}} E \stackrel{(h)}{=} \mathbf{A}_{1}^{j} \mathbf{A}_{2}^{j} \stackrel{(m)}{=} \frac{g_{i;t+1}}{f_{i;t+1}} + \stackrel{h}{=} \mathbf{B}_{1}^{j} \mathbf{B}_{2}^{j} \stackrel{(m)}{=} \frac{g_{i;t}}{f_{i;t}} / \frac{j}{i;t};$$
(1)

for all  $i \ge [0;1]$  and t = 0;1;:::. Here,  $f_{i;t} = [-f_{i;t}, f_t^a]$  is an exogenous column vector of stochastic variables. In analogy to the endogenous vector  $g_{i;t}$ , we partition the exogenous vector into an atomistic component,  $-f_{i;t}$ , and an aggregate component,  $f_t^a$ , where the atom-

<sup>&</sup>lt;sup>3</sup>Here, ex ante symmetry across *i* means that the unconditional distribution over  $I_{i;t}^{j}$  is identical across all *i*. While di erences in the ex-post realization of signals can also be captured by introducing additional information classes, using *i* to re ect these di erences helps streamlining notation in models where (some) agents are ex-ante identical.

<sup>&</sup>lt;sup>4</sup>Notice that which variables are realized at date t is de nitional and, thus, something the modeler must specify. For instance,  $/_t$  could contain future innovations if they are realized at date t as in the news literature.

istic component satis es the adding up constraint  $\begin{bmatrix} R_1 \\ 0 \end{bmatrix} f_{i:t} di = 0$ . We assume that  $f_{i:t}$  follows a stationary Gaussian process and is ex-ante symmetric across *i*.<sup>5</sup>

Throughout, we maintain the assumption of rational expectations, so that conditional on an information set, all expectations are formed using Bayes law. An equilibrium is de ned as a joint process for all the endogenous variables,  $f g_{i;t}$ 

To do so, we impose the following structure on information in the original economy.

### Assumption 1 (Information bounds). $j_{i,t} = l_{i,t}^j = l_{t}^j$ .

Assumption 1 de nes a lower and an upper bound on information. The upper bound,  $I_t$ , simply states that agents cannot learn more than what is potentially knowable under full information. The lower bound,  $\frac{j}{i;t}$ , must be specified by the modeler. It constitutes the primary input parameter to our methodology, allowing researchers to explore how their priors regarding agents' information restricts equilibrium outcomes.

#### Assumption 2 (Recursiveness). $I_{i;t-1} = I_{i;t}$ :

Assumption 2 imposes the usual rationality requirement that all agents perfectly recall past information. While perfect recall is standard, we note that our methodology easily extends to the case where agents may forget past information.<sup>6</sup>

To state the theorem, de ne

$$\int_{i;t} E_t[\mathbf{A}_1^j g_{i;t+1} + \mathbf{A}_2^j f_{i;t+1} + \mathbf{B}_1^j g_{i;t} + \mathbf{B}_2^j f_{i;t}] + \int_{i;t'} f_{i;t'}$$

which for each (i; j; t) represents the expectation implicit in  $\int_{i;t}^{j}$ . The following theorem states the implementation result.

**Theorem 1.** Fix stationary F, T and  $E \ge E^{\text{primal}}(F;T)$ . Then there exists an information structure I satisfying Assumptions 1 and 2 that implements E as equilibrium in the incomplete-information economy (i.e.,  $E \ge E(F;I)$ ) if and only (i)  $E\begin{bmatrix} j\\i:I \end{bmatrix} = 0$  and (ii)

$$E[ \frac{j}{i;t} ] = 0 \text{ for all } 2f \frac{j}{i;t} \frac{j}{s'} g_{s 0}$$
(3)

#### hold for i, j, and t.

The theorem gives two conditions that are jointly necessary and sull cient for T to be implemented by some information structure. Condition (i) is simply a rationality requirement that an agent's beliefs cannot be perpetually biased. Condition (ii) is an orthogonality requirement between the expectation wedges and  $\int_{i,t}^{j}$  and  $\int_{i,t}^{j}$ . The necessity of this restriction is the familiar result that expectation errors must be orthogonal to all available information, including an agent's belief  $\int_{i,t}^{j}$  itself (at the very least \one knows what one knows"). The novel part of our result is the sull ciency of this condition. For any  $E \ 2 \ E^{primal}(F;T)$  with  $E[T_t] = 0$ , we can always construct an information structure that implements E as an incomplete-information equilibrium as long as it satis es (3).

<sup>&</sup>lt;sup>6</sup>Speci cally, in this case, we obtain a version of our theorem, in which condition (3) is imposed only for s = 0.

the log-linearly approximated pricing decision of a monopolistically competitive rm, while taking aggregate demand as an exogenous process in the spirit of Woodford (2003).

Setup Firms in the model set their prices according to

$$\rho_{i;t} = E[\rho_t + y_t + z_{i;t}j/_{i;t}];$$
(8)

where  $p_t = \begin{bmatrix} R_1 \\ 0 \end{bmatrix} p_{i;t} di$  is the aggregate price index,  $y_t$  is aggregate output,  $z_{i;t}$  is an idiosyncratic demand shock, and 2(0;1) and 2[0;1] are the elasticities of the target price in  $y_t$  and  $z_{i;t}$ . Each rm *i*, faces standard CES demand,

$$y_{i;t} = (p_{i;t} \quad p_t) + y_t + z_{i;t};$$
 (9)

with > 1: Finally, aggregate output and prices are related via the constant-velocity equation

$$q_t = y_t + \rho_t$$
(10)

with  $q_t$  denoting the exogenous supply of money. We assume that  $fz_{i;t}g$  and  $q_t$  follow independent stationary Gaussian processes, and  $\begin{bmatrix} R_1 \\ 0 \end{bmatrix} z_{i;t} di = 0$ .

**Primal representation** Because only (8) contains an expectation, it is the only equation with a non-trivial expectation wedge in the primal representation of the economy. The primal representation of the economy is therefore given by

$$p_{i;t} = p_t + y_t + z_{i;t} + z_{i;t}$$
(11)

along with equations (9) and (10).

Given a process  $f_{i;t}g_i$  the equilibrium of the primal economy is straightforward to nd. Defining  $t = \begin{bmatrix} R_1 \\ 0 & i;t \end{bmatrix} d_i$ , aggregates in the economy are given by

$$p_t = q_t + \frac{1}{t} \quad y_t = \frac{1}{t} \quad (12)$$

an exogenous aggregate shock to generate any expectation-driven uctuations in aggregate output. As we explore in our more general quantitative setting, this conclusion is an artifact of two simplifying assumptions: (i) the assumption that rms observe their own sales,  $y_{i;t} = \sum_{i;t} y_{i;t}$  which precludes rms from having uncertainty about their demand, and (ii) the absence of other rm-speci c shocks a ecting input prices or technology. Once we relax either of these assumptions, it will be possible to generate expectation-driven uctuations in the absence of aggregate shocks. Before further exploring this possibility, we rst demonstrate how one can use our methodology to establish related bounds on the co-movement between output, in ation and money growth.

**Proposition 2.** In ation t  $p_t$   $p_{t-1}$  and money growth  $dq_t = q_t$   $q_{t-1}$  must be weakly procyclical. Speci cally, the correlation with output is bounded below as follows:

$$P \overline{\operatorname{Var}[y_t]}$$
 (1 )  $\frac{\operatorname{Corr}[y_t; t]}{1 \operatorname{Corr}[y_t; y_{t-1}]} P \overline{\operatorname{Var}[t]}$ 

and

$$\stackrel{[\mathsf{p}]}{\mathsf{Var}[y_t]} \quad \frac{(1)}{(1)} \quad + \quad \frac{\mathsf{Corr}[y_t; \mathsf{d}q_t]}{1 \quad \mathsf{Corr}[y_t; y_{t-1}]} \stackrel{[\mathsf{p}]}{\mathsf{Var}[\mathsf{d}q_t]}$$

*Proof.* As both bounds are derived following completely analogous steps, we only show the proof for in ation. Evaluating (16) for s = 0 and s = 1, using (12) to substitute for t, and di erencing the resulting conditions, we have

$$Cov[y_t; dy_t]$$
 (1 ) $Cov[y_t; ] = {}^{1}Cov[{}_{i;t}; d {}_{i;t}]:$ 

Noting that Cov[  $_{i;t}d _{i;t}] = (1 \quad Corr[$   $_{i;t}d _{i;t-1}]) \quad Var[$   $_{i;t}] \quad 0 \text{ completes the proof.}$ 

The proposition establishes that, when uncertainty originates exclusively from demand shocks, expectations-driven uctuations must exhibit exactly the same cyclical properties as demand shocks themselves. Again, the restriction is especially stark given the assumptions of our simple model, and the restriction that in ation and money growth must be procyclical is relaxed once we allow for other sources of uncertainty.

We conclude our illustration by exploring two re nements of *i*:*t*.

### **Proposition 3.** Suppose $f_{z_{i;t}}$ , $y_{i;t}g_{2} = i;t$ . Then aggregate output is constant.

*Proof.* Using (9) to substitute out  $y_{i;t}$  in (15), and combining with (14) to eliminate  $p_{i;t}$ , we obtain

$$Cov[t; y_{t-s} + p_{t-s}] = Cov[t; z_{i;t-s}]:$$
(18)

From  $\underset{i;t'}{R} z_{i;t} di = 0$ , it follows that  $Cov[ i;t' z_{i;t-s}] = Cov[ i;t' z_{i;t-s}]$ . Applying Theorem 1, it then must hold that  $Cov[ i;t' z_{i;t-s}] = 0$ . Evaluating (18) at s = 0 and s = 1, using (12) to substitute for t

a representative rm in a local labor market. Firms use the labor provided by households to produce di erentiated intermediate goods, which are aggregated by a competitive nal goods sector located on the mainland. There are no subperiods; all markets at date *t* operate simultaneously.

Households Preferences on island *i* are given by

$$E = 0 \begin{pmatrix} ( & ) \\ ( &$$

where 2(0;1) is the discount factor,  $N_{i;t}$  is hours worked,  $C_{i;t}$  is nal good consumption, and  $I_{i;t}^{h}$  denotes the information available to the household on island *i* at time *t*. The utility ow *U* is given by

$$U(C; N) = \log C + \frac{1}{1+N^{1+}};$$

where 0 is the inverse of the Frisch elasticity of labor supply. The household's budget constraint is

$$P_t C_{i;t} + Q_t B_{i;t} - W_{i;t} N_{i;t} + B_{i;t-1} +$$

speci c component,

$$\log A_{i;t} = \log A_t + a_{i;t}$$

where the aggregate component follows a random walk process

$$\log A_t = \log A_{t-1} + t$$

The innovation t is i.i.d. across time with zero mean and constant variance. The islandspeci c component  $a_{i;t}$  follows a time-invariant, stationary random process that is i.i.d. across islands and is normalized so that  $\begin{bmatrix} R_1 \\ 0 \end{bmatrix} a_{i;t} di = 0.$ 

**Final-good sector** A competitive nal-goods sector aggregates intermediate input goods  $i \ge [0;1]$ , using the technology

$$Y_t = \int_{0}^{Z_{i;t}} Z_{i;t} Y_{i;t}^{-1} di$$

where > 1 is the elasticity of substitution among input varieties,  $Y_{i;t}$  denotes the input of intermediate good *i* at time *t*, and  $Z_{i;t}$  is an island-speci c demand shifter following a time-invariant, stationary process that is i.i.d. across islands and satis es  $\binom{R_1}{0} \log(Z_{i;t}) di = 0$ . Pro t maximization yields the inverse input demands, given by

$$P_{i;t} = \frac{Y_{i;t}}{Y_t} \sum_{i;t}^{1=1} Z_{i;t} P_t;$$
(20)

where the aggregate price index  $P_t$  is defined by

$$P_t = \int_{0}^{Z_{1}} Z_{i;t} P_{i;t}^{1} di =$$

**Monetary policy** We close the model by specifying a simple interest rate rule, pinning down the equilibrium rate of in ation,  $t = \log(P_t = P_{t-1})$ . Speci cally, we assume that the central bank sets nominal bond prices such that

$$i_t = t^{\prime} \tag{21}$$

 $<sup>\</sup>left( \begin{bmatrix} R_{1} & Y_{ij,t}^{1-1} & dj \end{bmatrix}^{-1} \right)$  where matches the elasticity of substitution across \island-varieties" specied in the

where > 1 and  $i_t = \log(Q_t)$ .<sup>9</sup>

**Information structure** Our methodology allows us to explore how a few abstract assumptions regarding  $fl_{i;t}^{j}g_{i;j,2[0;1]}$  ff;hg

### 3.2 Equilibrium Conditions

We work with a log-linear approximation to the model around the balanced growth path of the economy with no heterogeneity and full information. Lower-case letters denote log-deviations of a variable from this path, in which  $y_{i;t} = a_t$  for all *i* and t = 0.

The households' Euler equation is given by

$$C_{i,t} = \mathbb{E}[C_{i,t+1} + t_{t+1}j/\frac{h}{i,t}]:$$
(25)

Combining rms' demand for labor with households' supply, local labor market clearing requires

$$y_{i;t} = y_{i;t} \quad c_{i;t} + \mathbb{E}[p_{i;t}/f_{i;t}] \quad \mathbb{E}[p_t/f_{i;t}] + a_{i;t};$$
(26)

where 1=(+1). The linearized price index  $p_t$  is given by  $p_t = {\binom{R_1}{0}} p_{i,t} di$ . The linearized demand relation and budget constraint take the form

$$\rho_{i;t} = {}^{1}(y_t \quad y_{i;t}) + z_{i;t} + \rho_t$$
(27)

and

$$b_{i;t} = b_{i;t-1} + y_{i;t} - c_{i;t} + p_{i;t} - p_{t'}$$
(28)

where  $b_{i;t} = B_{i;t} = (P_t C_{i;t})$  is in levels rather than logs because  $B_{i;t}$  can take negative values. Given a process for fundamentals and information  $fa_{i;t}, z_{i;t}, f_{i;t}, f_{i;t}, g_{i;t}$  an equilibrium of the model is a set of processes  $fc_{i;t}, y_{i;t}, b_{i;t}, p_{i;t}g$  and  $fy_{t}, g$  that are consistent with (25){(28), with Bayesian updating, and with market clearing for goods,

$$y_t = \int_{0}^{Z_{1}} y_{i;t} di = \int_{0}^{Z_{1}} c_{i;t} di:$$
(29)

(As usual, market clearing for bonds is implied by (28) and (29).)

**Comment on prices**, **information**, **and market clearing** In many general equilibrium models with incomplete information it is relatively simple for agents to infer the value of the economy's aggregate fundamentals from observing aggregate prices. As argued by Lorenzoni (2009), this is largely an artifact of the simplicity of models, whereas, in practice, the ability of agents to learn about the economy's fundamentals is likely impaired by a large number of shocks, model misspeci cation, and the possible presence of structural breaks. To capture these e ects within simple models like ours, the literature has therefore utilized various ways

of introducing noise into price systems.<sup>11</sup>

In keeping with the literature, we do not include the real return on assets,  $r_t$   $i_t \in_t[t_{t+1}]$ , or its constituents  $i_t$ ,  $p_t$  and  $\mathbb{E}_t[p_{t+1}]$ , in the lower bound on households' information  $f/\frac{h}{l_tt}g$ . However, we note that by imposing market clearing on the aggregate goods market, we *implicitly* require that households observe some noisy version of  $r_t$  such that the average expected real interest  $\mathbb{E}_t[r_t]$  increases with  $r_t$ . Using our methodology, there is no need to explicitly specify the signals through which households make inference about  $r_t$ . Instead, requiring market clearing in the primal representation of the economy yields by construction a \market clearing expectation''  $\mathbb{E}_t[r_t]$  that adapts to clear the goods market in all states of the world.<sup>12</sup>

To see this, consider the simpli ed case where aggregate demand is given by  $c_t = E[r_t j/t]$ and aggregate supply,  $y_t$ , follows an exogenous random process. In this case, market clearing  $(c_t = y_t)$  requires

$$\mathsf{E}[r_t j | t] = y_t; \tag{30}$$

which in conjunction with  $/_t$  pins down  $r_t$ : In the primal representation,  $E[r_t//_t] = r_t + t_t$ , and market clearing requires

$$r_t + t = y_t$$
(31)

The key di erence between (30) and (31) is that the expectation error, t, is a primitive of the primal economy. Because t is exogenous in the primal economy, the solution  $r_t = y_t t$  always imposes that the implied  $E[r_t/t_t]$  responds one-for-one to a decline in  $y_t$ , inducing precisely the sensitivity of households' expectations to economic conditions that is necessary for  $r_t$  to clear the goods market. Hence, by imposing market clearing in the primal economy, preciseltion Tf 2e 6 42988(in) - 2.794 283 9701 Tz0. We implicitly require that agents have enough informatiompreciseltion Tf 2e.6ng

# 3.3 Primal Representation

There are two equilibrium conditions with non-trivial expectation operators. Replacing equations (25) and (26) with their primal analog, we arrive  $at^{13}$ 

 $C_{i;t} = E$ 

and, using d() to denote the st di erence of a variable, x

$$E_t = f dc_{i;t} dy_{i;t} db_{i;t} db_{i;t} dp_{i;t} g_{i2[0;1]} [ f dy_t; tg 2 E(F;T):$$

Then there exists an information structure l satisfying Assumptions 1{3 that implements E as equilibrium in the incomplete-information economy if and only if (i)  $\begin{pmatrix} c & p;h, p;f \\ i;t' & i;t' & i;t' \end{pmatrix}$  follows a MA(h) process of order h < h, (ii)  $E[\begin{pmatrix} c & p;h, p;f \\ i;t' & i;t' & i;t' \end{pmatrix}] = 0$ , and (iii)

$$E\begin{bmatrix} c\\i;t \end{bmatrix} = E\begin{bmatrix} p;h\\i;t \end{bmatrix} = 0 \quad for \ all \qquad 2 \ fS_{i;t}^h \ _sg_{s=0}^{h-1}; and \\ E\begin{bmatrix} p;f\\i;t \end{bmatrix} = 0 \quad for \ all \qquad 2 \ fS_{i;t}^f \ _sg_{s=0}^{h-1}$$

hold for all i and t.

Proposition 5 is an immediate corollary to Theorem 1. Here, the restriction to nite MA processes arises because /

captured by  $t^p$   $t^{p;f}$   $t^{p;h}$ , which corresponds to the labor wedge in our economy that is composed of a household and a rm component. The aggregate \wedges''  $t^c$  and  $t^p$  are the sole drivers of the output gap and in ation. If all agents had full information ( $t^c_t = t^p_t = 0$ ), the aggregate economy would be in its rst-best equilibrium in which output reaches its potential in every period ( $y_t = a_t$ ) and in ation is always zero.

In general, a solution for endogenous variables as a function of the joint process  $t = (\begin{array}{c} c \\ t \end{array} \\ \begin{pmatrix} c \\ t \end{array} \\ \begin{pmatrix} p \\ t \end{pmatrix}^{\ell}$  can be obtained using standard numerical tools. In our case, a closed-form solution is also available. Substituting for  $f_t$  in (34), t is characterized by the prediction formula

 $_{t} = {}^{1} \mathbb{E}_{t} [ d _{t+1}^{p} d _{t+1}^{c} + _{t+1}]:$ (36)

Following Hansen and Sargent (1980, 1981), we obtain an explicit solution for in ation, stated in the following.

**Lemma 1.** Let  $_t = A(L)u_t$ , where A(L) is a square-summable lag polynomial in non-negative powers of L and the innovations  $u_t$  are orthogonal white noise. Then there exists a unique stationary equilibrium process for  $(\mathfrak{F}_t; t)$ , given by

$$\hat{y}_t = \begin{array}{c} h & i \\ 0 & A(L)u_t \end{array}$$
(37)

and

$$_{t} = {\overset{h}{1}} 1 {\overset{i}{\frac{(1 - L)A(L)}{L}} {(1 - {\overset{1}{1}})A({\overset{-1}{1}})} u_{t}} u_{t}$$
(38)

## 4 Inference About the Aggregate Economy

In this section, we explore how the theoretical restrictions of Proposition 5 translate into restrictions on the behavior of the aggregate economy. In a rst step, Section 4.1 maps the restrictions stated in Proposition 5 into restrictions on the dynamics of the \macro" wedges determining the behavior of the aggregate economy. Sections 4.2 and 4.3 then use these restrictions on the macro wedges to characterize feasible volatility and co-movement patterns of output and in ation under varying assumptions on information and fundamentals.

### 4.1 Feasible Dynamics of Aggregate Wedges

We begin by mapping the orthogonality restrictions in Proposition 5 into restrictions on the macro wedges  $\frac{c}{t}$  and  $\frac{p}{t}$ . To streamline the exposition, we only detail the derivation

for the baseline case  $\int_{i,t}^{sym}$  depicted in (22), in which rms and households have symmetric information.

To begin, observe that for  $\sup_{i;t} f_{i;t} g_{i;t} g_{s,0}$  satis es Assumption 3 with

$$S_{i;t} = f dc_{i;t} dy_{i;t} da_{i;t}g$$

Here we have used that (i)  $n_{i;t}$  and  $w_{i;t}$  are linear combinations of  $(c_{i;t}, y_{i;t}, a_{i;t})$  and are therefore informationally redundant; and (ii) that for any nite horizon  $h_i$  observing the sequence of *di erences*  $fS_{i;t}$   $_{s}g_{s=0}^{h-1}$  in addition to  $I_{t-h}$  contains the same information as the corresponding sequence of *levels*.

To proceed, de ne  $_{i;t}$   $(\begin{array}{cc} c & p;h & p;h \\ i;t' & i;t' & i;t' \end{array})^{\ell}$  and let  $_{i;t}$   $_{i;t}$   $_{t}$  denote the idiosyncratic portion of the expectation wedges. Similarly, let  $(\begin{array}{cc} c_{i;t'} & y_{i;t} \end{array})$  denote the idiosyncratic deviations from aggregate output. By construction the \Delta"-component of any variable is

and the (auto-)covariance structure of the economy, which can be characterized numerically.

For our numerical analysis below, we exploit that for any (zero mean) MA(*h*) process for the idiosyncratic and aggregate components of  $_{i;t}$ , condition (39) is both necessary and su cient for the implementation of these wedges by some information structure. The set of feasible aggregate uctuations is thus characterized by the set of aggregate processes  $f \stackrel{c}{t} \stackrel{p}{t} g$  for which (39) can be satis ed with some processes for the idiosyncratic components  $f \stackrel{c}{l} \stackrel{p}{t'} g$ . In general, one can obtain this characterization by numerically solving for the map from wedges to covariances, which entails nding equilibrium in the \Delta"-economy. In our case, we are able to simplify the search by solving the \Delta-economy" in closed form, which allows for a more e cient numerical implementation (see the derivation following Lemma 2 in the Online Appendix for details.)

#### 4.2 Unrestricted Micro-Shock Benchmark

Before proceeding to our quantitative results, we provide a theoretical benchmark for the case where we treat the idiosyncratic fundamentals,  $f_{i;t} = (a_{i;t}; z_{i;t})$ , as unrestricted. Previous literature has shown that if idiosyncratic fundamentals are su ciently volatile, then confusion about these shocks can be used to support aggregate uctuations in  $\hat{y}_t$ , even if there are no aggregate shocks to fundamentals. This is because expectation errors regarding *local* shocks can be correlated across islands even though the underlying fundamentals are purely idiosyncratic (e.g., Angeletos and La'O, 2013; Benhabib, Wang and Wen, 2015).

In the spirit of this literature, the following benchmark uses our methodology to characterize what dynamics are possible if we place no restrictions on  $f_{i;t}$ . By construction, the chosen process for  $f_{i;t}$  has no direct impact on the aggregate economy. Its only role is to provide a source of uncertainty, which can be used to support aggregate uctuations when information is incomplete.

**Proposition 6.** Fix a (zero mean) MA(h) process for  $\begin{pmatrix} c & p \\ t' & t \end{pmatrix}$  and set  $\sup_{i;t}$  as in (22). Then for any aggregate productivity process, a, there exist idiosyncratic processes and *f*, such that can be implemented in the incomplete information economy.

Proposition 6 provides a striking benchmark: Absent micro-data that disciplines  $f_{i;t}$ , correlated optimism and pessimism (across islands), can be used to generate *any* joint process in  $(\hat{y}_{t;-t})$ . Going beyond the results in Angeletos and La'O (2013) and Benhabib, Wang and Wen (2015) on *volatility*, the benchmark shows that \sentiment" uctuations can implement arbitrary *processes* for  $_t$  and, by implication, arbitrary autocorrelation structures among the aggregate variables, potentially bypassing all cross-equation restrictions that emerge under

full information.<sup>14</sup> Intuitively, expectation errors can plausibly be correlated, both because information can be correlated between households and rms and because expectation errors by households generally a ect both their consumption and labor supply.

## 4.3 Quantitative Results

In light of the \everything goes" result in Proposition 6, a natural question to ask is: what are the restrictions on aggregate dynamics once we  $x = f_{i,t}$  at an empirically plausible calibration? We explore this question numerically, calibrating  $= f_{i,t}$  to existing micro-data.

**Parametrization** We interpret one period as a quarter, and set the discount factor to 0.99. The inverse Frisch elasticity is set to 0.5, the elasticity of substitution between input varieties is set to 7.5, and the elasticity of the interest rate is set to 1.5. These values are within the range typically used by the literature.

Next, we set the incomplete information horizon to h = 14 quarters. While we do not *h* ave strong priors ed,

 $z_{i;t}$  and  $a_{i;t}$  that match the corresponding statistics in Foster, Haltiwanger and Syverson (2008).<sup>15</sup>

It is worth noting that, in line with popular views, the data of Foster, Haltiwanger and Syverson (2008) imply that demand shocks are much larger than productivity shocks (see also Loecker 2011; Demidova, Kee and Krishna 2012; Roberts et al. 2017; Foster, Haltiwanger and Syverson 2016 for similar results). Intuitively, this is consistent with the idea that uctuations in demand re ect both demand and supply shocks upstream in the production chain, which ampli es demand uncertainty relative to the uncertainty about within- rm technology. We explore the robustness of our results with respect to the scale of idiosyncratic shocks, considering a variety of calibrations in the exercises that follow.

**Volatility frontier (de nition)** We compute the maximal output volatility | as a function of its persistence and the cyclicality of in ation | that our model can generate in the absence of aggregate shocks to fundamentals (Var[ $_t$ ] = 0). Formally, de ne  $_{\psi}()$   $\Pr \overline{Var[\psi_t/l_{t-1}]}$  as the one-step-ahead volatility of output induced

Formally, de ne  $_{\hat{y}}() \xrightarrow{} Var[\hat{y}_t/t_1]$  as the one-step-ahead volatility of output induced by . Similarly, de ne  $_{\hat{y}}() \xrightarrow{} Corr[\hat{y}_t; \hat{y}_{t-1}]$  as the rst-order autocorrelation of  $\hat{y}_t$ , and de ne  $_{\hat{y}}() \xrightarrow{} Corr[\hat{y}_t; _t]$  as the contemporaneous correlation with in ation. We use Lemma 2 to numerically trace out the *volatility frontier* for output as a function of its autocorrelation  $_{\hat{y}}$ and its contemporaneous correlation with in ation  $_{\hat{y}}$ :

$$\max_{y}(y;y) \max f_{y}(y)g$$

subject to

$$y() = y$$
  
 $y() = y$ 

and the implementability condition (39). Here and are independent (zero-mean) MA(*h*) processes.



gure.

The sensitivity is strongest in z and  $z_i$  indicating that correlated expectation errors about the demand shocks  $fz_{i;t}g$  are of critical importance for supporting uctuations in aggregate con dence. In particular, a reduction in z from its baseline value of 0.2504 to 0.01, reduces  $\frac{max}{y}$  by a factor of three to 0.37 percent; an increase in z to 1.00, increases  $\frac{max}{y}$  to 3.39 percent. Those comparative statics re ect the naturally increasing shape of  $\frac{max}{y}$  in any fundamental volatility. Intuitively, the more volatile  $z_{i;t}$  (and  $a_{i;t}$ ), the larger the potential for agents to make expectation errors, which is a direct consequence of the law of total variance (Var[ $Efz_{i;t}j/_{i;t}g$ ] Var[ $z_{i;t}$ ]). In the extreme case where  $z \neq 0$ , rationality requires that  $E[z_{i;t}j/_{i;t}g] = 0$  for all  $t_i$  even if  $f_{i;t}$  contains no information about  $z_{i;t}$ .

Similarly to  $z_i$ , variations in the persistence of  $z_{i;t}$  also have a signi cant impact on  $\frac{\max}{y}$ : a reduction of z from its baseline value of 0.976 to 0.5, reduces  $\frac{\max}{y}$  to 0.35 percent. An increase in the persistence of  $z_{i;t}$  to 0.99, increases  $\frac{\max}{y}$  to 3.18. The role of z for supporting expectation errors is two-fold. First,  $\operatorname{Var}[z_{i;t}]$  is increasing in  $z_i$  again increasing the potential for expectation errors. Second, persistence in  $z_{i;t}$  (or in  $a_{i;t}$ ), enables optimism and pessimism regarding the wealth of the local household, independently from the direct e ects on contemporaneous labor supply and demand. As uctuations in *perceived* wealth translate into uctuations in desired consumption, they can be used to induce pro-cyclical in ation dynamics as in Lorenzoni (2009), which is instrumental for generating the targeted cyclicality of in ation (y = 0.3).<sup>19</sup>

By contrast, variations in the parameters of  $fa_{i;t}g$  result in only moderate variations in  $\overset{\text{max}}{\overset{y}{}}$ . In particular, reducing  $\overset{x}{\overset{y}{}}$  or  $\overset{y}{\overset{z}{}}$  to 0.01, implies only marginally smaller values of  $\overset{\text{max}}{\overset{y}{}}$ , suggesting that the idiosyncratic productivity shocks  $f = a_{i;t}g$  play a somewhat dispensable role in our calibration. This rejects two factors. First, given our calibration, productivity is less volatile than demand, implying that there is less scope for productivity-related confusion in the rst place. Second, because  $a_{i;t} 2 = i;t$ , rms and households always know their current productivity, limiting productivity-related confusion to uncertainty about the composition of

 $a_{i;t}$ , whose relevance in turn is determined by the persistence of  $x_{i;t}$ .

**No demand uncertainty** So far, we have not taken a stand whether or not agents know the inverse demand for the local good,  $p_{i;t}$ . As an alternative, we now consider the case where  $p_{i;t}$  is perfectly observed, so that there is no uncertainty about the revenues associated with

<sup>&</sup>lt;sup>19</sup>In order to generate pro-cyclical in ation dynamics through optimism and pessimism about  $z_{i;t}$ , the information structure must mute the direct substitution e ect on labor demand. This can be achieved, for instance, by making agents (su ciently) informed about  $p_{i;t}$  (coupled with some nominal misconception as in Lucas (1972, 1973), so that  $p_{i;t}$  does not fully reveal  $z_{i;t}$ ), which is a su cient statistic about  $\mathbb{E}[z_{i;t}/t_{i;t}]$  for determining labor demand.

a particular choice of production. Formally, information is now bounded by

$$i_{i,t} = f p_{i,t} g_{s 0} \begin{bmatrix} sym \\ i_{i,t} \end{bmatrix}$$

with  $_{i;t}^{\text{sym}}$  given by (22). Because  $_{i;t}^{p;f}$  measures rms' expectation error regarding  $p_{i;t_i}$  an immediate consequence of including  $p_{i;t_i}$  in  $_{i;t_i}^{f}$  is that  $_{i;t_i}^{p;f} = 0$  for all *i* and *t*, so that uctuations in aggregate output can only be driven by the households' component of the labor wedge. Intuitively, rms only need to know their marginal costs,  $w_{i;t_i} = a_{i;t_i}$  and their local demand,  $p_{i;t_i}$  to behave *as if* they have full information (see also Hellwig and Venkateswaran, 2014).

For the baseline parametrization of  $f_{i;t} z_{i;t}g_i$ , shutting down  $t_t^{p;f}$  reduces  $y_t^{max}$  to 0.41, suggesting that uncertainty about demand is key to generating sizable aggregate uctuations. Moreover, compared to the case where  $t_{i;t}^{sym}$  is given by (22), the sensitivity of  $y_t^{max}$  in the parameters of  $fz_{i;t}g$  is reduced, whereas the sensitivity in the parameters of  $fa_{i;t}g$  is heightened (illustrated by the gray squares in Figure 2). This is because when  $p_{i;t}$  is known, agents can back out the state of  $z_{i;t} + p_t$   $y_t$  from (20), reducing the scope to generate waves of optimism and pessimism via  $z_{i;t}$  and, by implication, increasing the model's reliance on  $a_{i;t}$  for supporting aggregate uctuations in con dence.<sup>20</sup>

**Heterogeneous information** We next relax the assumption that households and rms share the same information set, setting  $\frac{h}{l;t}$  and  $\frac{f}{l;t}$  as in (23) and (24). The resulting volatility frontier is depicted by the red lines in Figure 2. For the baseline calibration, this increases  $\frac{max}{y}$  to 4.49 percent. This re ects the additional exibility in  $\int_{i;t}^{f}$  and  $\int_{l;t}^{h}$  due to households not being required to perfectly know the local rm's productivity (i.e.,  $a_{l;t}, y_{l;t} \ge \frac{h}{l;t}$ ) and rms not being required to perfectly know households' consumption ( $c_{l;t} \ge \frac{f}{l;t}$ ). Speci cally, this enables waves of optimism and pessimism among households about incomeuctuations caused by  $a_{l;t}$  and  $z_{l;t}$ , translating to aggregate demand uctuations | even if  $a_{l;t}$  and  $z_{l;t}$  are observed by rms. The stark increase in  $\frac{max}{y}$  suggests that the usual assumption of symmetric information may in fact be quite restrictive.

Finally, we explore a variant of the heterogeneous information setting where rms face no demand uncertainty ( $\int_{i;t}^{r}$  includes  $fp_{i;t} g_{s=0}$  in addition to (24)). The results are depicted by the blue lines in Figure 2). Compared to the symmetric-information case without demand uncertainty,  $\int_{v}^{max}$  is slightly increased to 0.49. However, the di erence between symmetric

<sup>&</sup>lt;sup>20</sup>The sensitivity in  $z_{i;t}$  is not reduced to zero for two reasons. First,  $z_{i;t}$  serves as noise about the aggregate state. Second, despite there being no uncertainty about *current*  $p_{i;t}$ , expectation errors about  $z_{i;t}$  continue to translate into optimism and pessimism about *future* prices whenever  $z \notin 0$ , which a ects local wealth and households' consumption choice.

		Contemporaneous correlation		
Standard deviation	- First-order autocorr.	with $^{c}_{t}$	with ${}^{\wedge p}_{t}$	

Table 1: Summary of estimated U.S. wedges

#### 5.1.2 Partitioning of the estimated wedges

We partition the estimated wedge process  $_{t}^{t}$  into an informational component  $_{t}^{info}$  and a residual component  $_{t}^{resid}$ ,

$$\hat{t}_t = \frac{\inf_t 0}{t} + \frac{\operatorname{resid}}{t}.$$
 (42)

In parallel to  $_{t_i}$  we model both components as statistically independent MA(14) processes,

$$\underset{t}{\overset{\text{info}}{\text{info}}} = \overset{\text{info}}{u}(L) \underset{t}{\overset{\text{info}}{\text{info}}} + \underset{u}{\overset{\text{info}}{\text{info}}}(L) \underset{t}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{resid}}}(L) \underset{t}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{info}}}(L) \underset{t}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{\text{resid}}{\text{info}}} + \underset{u}{\overset{u}} + \underset{u}{\overset{u}}$$

where <sup>info</sup>, <sup>info</sup>, <sup>resid</sup> and <sup>resid</sup> are square-summable lag polynomials in non-negative powers of *L*. The innovations, <sup>info</sup>, <sup>resid</sup>,  $u_t^{info}$  and  $u_t^{resid}$ , are mutually orthogonal white noise. In particular, <sup>info</sup> and <sup>resid</sup> are innovations to aggregate productivity, satisfying

$$\hat{t}_t = \frac{\inf_t f}{t} + \frac{\operatorname{resid}}{t}, \tag{43}$$

with standard deviations <sup>info</sup> and <sup>resid</sup>. The corresponding lag-polynomial <sup>info</sup> captures how incomplete information regarding  $a_t$  in uences the propagation of productivity shocks.<sup>23</sup> The innovations  $u_t^{info}$  and  $u_t^{resid}$ , each two-dimensional, are intrinsic shocks to  $t_t^{info}$  and  $t_t^{resid}$ . Accordingly, the lag-polynomial  $u_u^{info}$  de nes intrinsic uctuations in  $t_t^{info}$ , driven by expectation errors, whereas  $u_u^{resid}$  de nes intrinsic uctuations in the residual wedges  $t_t^{resid}$ .

The de ning di erence between  $t_t^{info}$  and  $t_t^{resid}$  is that we impose the conditions of Theorem 1 on  $t_t^{info}$ , whereas  $t_t^{resid}$  remains unrestricted. We gauge the potential role of incomplete information for explaining the U.S. business cycle by maximizing the contribution of expectation errors  $u_t^{info}$  to the Itered variance of  $\hat{y}_t$ . Let  $\hat{y}_t^{fp} = \mathbb{E}[\hat{y}_t/(\hat{t}_s, \hat{t}_s)_{s=0}]$ ,  $\hat{y}_t^{info} = \mathbb{E}[\hat{y}_t/(\hat{u}_t^{info})_{s=0}]$ , and  $\hat{y}_t^{resid} = \mathbb{E}[\hat{y}_t/(\hat{u}_t^{esid})_{s=0}]$  denote the projection of the output gap on aggregate productivity, expectation errors, and residual shocks, respectively. Independence of the innovations implies  $\operatorname{Var}[\hat{y}_t] = \operatorname{Var}[\hat{y}_t^{tfp}] + \operatorname{Var}[\hat{y}_t^{info}] + \operatorname{Var}[\hat{y}_t^{resid}]$ . Then the maximal contribution of  $u_t^{info}$  is given by:

$$\max_{info \cdot resid \cdot info \cdot resid} Var[\hat{y}_t^{info}] = Var[\hat{y}_t]$$
(44)

<sup>&</sup>lt;sup>23</sup>Conversely, <sup>resid</sup> captures the e ects of other potential frictions in propagating productivity shocks. Splitting aggregate productivity into two independent innovations ensures that the volatility generated by incomplete information is independent of the residual wedges  $t^{\text{resid}}_{t}$ . If we instead let  $t^{\text{info}}_{t}$  and  $t^{\text{resid}}_{t}$  load jointly on the combined productivity shock t, we indicate the variance contribution of  $u^{\text{info}}_{t}$  almost arbitrarily through incomplete information regarding  $a_t$  and its propagation through  $t^{\text{resid}}_{t}$ . Below we also consider the case where agents perfectly observe aggregate productivity, in which case both settings give identical results.

standard deviations, (x; y; z), by up to 1 order of magnitude relative to the baseline calibration.<sup>24</sup> With the exception of the symmetric information benchmark, all speci cations allow households and rms to have access to potentially heterogeneous information.

### 5.2.1 Benchmarks

As benchmark, we rst consider the symmetric information case where  $\int_{l,t}^{sym}$  is set as in (22) and the heterogenous information case where  $\int_{l,t}^{h}$  and  $\int_{l,t}^{f}$  are set as in (23) and (24). In both cases, few restrictions are imposed on information beyond rational expectations. Perhaps not surprisingly in light of our theoretical benchmark in Proposition 6, con dence shocks can fully account for all U.S. business cycle uctuations unexplained by the productivity shock  $(Var[\hat{y}_{t}^{info}]=Var[\hat{y}_{t}/fa_{t-s}g_{s-0}]$  1), provided that  $(\sum_{x'=l}^{s'=l} z)$  are at least as volatile as in our baseline calibration (scale 1).<sup>25</sup> For the asymmetric information case (red line), the result is also robust to a downward-scaling of the micro-shocks by up to a factor of three. For the symmetric information case (blue dotted line), a reduction in the micro-volatilities by a factor of two (three), reduces the maximal contribution to 90 percent (67 percent).

### 5.2.2 Sentiments versus noisy learning about aggregate shocks

The benchmarks show that, in combination with productivity shocks, rational uctuations in con dence have the potential to fully account for the U.S. business cycle. We now take a closer look at which type of con dence uctuations are necessary to achieve this. Speci cally, we di erentiate between two types of con dence: (i) correlated con dence about *idiosyncratic* business conditions (aka \sentiment shocks"), and (ii) correlated con dence about *aggregate* productivity as in Angeletos and La'O (2010) or about future average productivity as in Lorenzoni (2009).

First, consider the case of sentiment shocks. We isolate their potential contribution by imposing perfect knowledge about the history of aggregate productivity by setting  $f_{i,t}$  and  $h_{i,t}$  as in (23) and (24), augmented by  $fa_t \ sg_s \ 0$ , eliminating any scope for TFP-driven uctuations in con dence. Comparing the resulting contribution (dashed green line) with the benchmark reveals that for *small* scales of the micro shocks, con dence about aggregate productivity is indeed key for explaining the data. On the other hand, when there is su cient idiosyncratic volatility (scale 3), sentiment shocks alone can do as well as the benchmark.

 $<sup>^{24}</sup>$ The scaling is applied to all three micro-shocks proportionately to their respective baseline values; i.e., the scaled standard deviations tw5sr8(e)-36n3(b)27(y)8334(a)]T

For the baseline calibration (scale = 1), sentiment shocks can account for 57 percent of non-productivity uctuations in U.S. output.

Next, consider the case without sentiment shocks. To eliminate them, we set  $f_{i;t}$  and  $h_{i;t}$  as in (23) and (24), augmented by  $fx_{i;t-s}; z_{i;t-s}g_s$ 

	Contribution to			
	Var[y <sub>t</sub> jfa <sub>t s</sub> g <sub>s 0</sub> ]	$Var[y_t]$	$Var[\hat{y}_t]$	
Heterogeneous info benchmark	1.00	0.89	0.64	
Symmetric info benchmark	0.99	0.89	0.63	
No TFP-driven con dence	0.57	0.51	0.36	
No sentiment-driven con dence	0.03	0.03	0.02	
No demand uncertainty	0.04	0.03	0.02	

Table 2: Implied variance contribution to U.S. output

Notes. | The table shows the share of output that can be accounted by the intrinsic shocks to the informational component of the estimated wedges,  $u_t^{info}$ . The contribution of the productivity shock to  $Var[y_t]$  and  $Var[y_t]$  is 11 and 36 percent, respectively. All variance contributions are computed at business cycle frequencies for the baseline calibration of  $f_{a_{i,t}g}$  and  $fz_{i,t}g$  (i.e., scale = 1 in Figure 3).

#### 5.2.4 Implied variance contribution to U.S. output

The results in Figure 3 show the business-cycle contributions to output volatility that is unexplained by productivity,  $Var[y_t j f a_t s g_{s 0}]$  (equivalently  $Var[y_t j f a_t s g_{s 0}]$ ). Table 2 computes the implied contribution to the overall volatility in  $y_t$  and  $y_t$ . The discrepancy between the three columns relects the contribution of the productivity shock to  $y_t$  and  $y_t$ . Looking at the contribution to  $y_t$ , sentiment-driven uctuations in condence can account for 51 percent of the empirical volatility. Importantly, however, for a theory of incomplete information to generate signi cant uctuations in condence, rms must face some uncertainty about their *idiosyncratic* product demands. If this is not the case, then condence uctuations can at most explain 3 percent of the empirical volatility in  $y_t$ .

# 6 Taking Stock

We have developed a method to quantify the potential of DSGE models with imperfect information without taking a fully structural stand on the private information of agents. Along the way, we established a *conditional* equivalence, which holds under the conditions of Theorem 1, between models with dispersed information and a prototype wedge-economy similar to the one in Chari, Kehoe and McGrattan (2007). The informational foundation for these wedges is distinguished from existing theories in its ability to generate arbitrary correlation patterns between these wedges (Proposition 6). Correlated wedges, in turn, are critical for the empirical viability of con dence uctuations because the data imply a strong correlation between the aggregate labor wedge and the Euler wedge.

Expectations are a natural candidate for generating the observed correlation, both because

information can be correlated between households and rms and because expectation errors by households generally a ect both their consumption and labor supply. Our results indicate, however, that two features are crucial to achieve a quantitively important role for such a foundation: (i) micro-shocks must be su ciently volatile and (ii) idiosyncratic demand must be uncertain at the time of production choices. Regarding (i), our analysis suggests that observed micro-level volatility is indeed large enough to support substantial aggregate volatility. Regarding (ii), the presence of idiosyncratic demand uncertainties has long been acknowledged in business practices (Fisher et al., 1994) and in operations research (Fisher and Raman, 1996; Mula et al., 2006). Yet, given the pivotal role that these uncertainties may play in supporting aggregate uctuations, our results suggest to us that further research is warranted regarding the degree to which rms misperceive their own demand shocks when making input choices.

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### A Proof of Main Theorem

Consider any expectation wedge  $\int_{i,t}^{j} 2 T_t$  from the primal economy and the corresponding lower bound  $\int_{i,t}^{j}$  on  $\int_{i,t}^{j}$  in the incomplete information economy. De ne the expectation \targets"

$$a_{i,t}^{j} = A_{1}^{j}g_{i,t+1} + A_{2}^{j}f_{i,t+1} + B_{1}^{j}g_{i,t} + B_{2}^{j}f_{i,t}$$

as pinned down by the equilibrium  $E \supseteq E^{primal}(F;T)$  of the primal economy.

We want to show that conditions (i) and (ii) are jointly necessary and su cient for the construction of some  $\int_{i;t}^{j} S_{i;t}^{j} + \int_{i;t-s'}^{j} \int_{i;t-s'}^{j} g_{s-0}$  such that

$$E[a_{i;t}^{j}/l_{i;t}^{j}] = E[a_{i;t}^{j}/l_{t}] + \frac{j}{l;t}$$
(45)

When this is true, any solution to (2) is trivially also a solution to (1).

To conserve notation, we suppress (i; j) subscripts going forward.

**Necessity** Necessity is immediate, since optimal inference requires that expectation errors are orthogonal to variables in the information set and are unpredictable. To see this, rearrange (45) to get

$$_{t} = \mathbb{E}[a_{t}j/_{t}] \quad \mathbb{E}[a_{t}j/_{t}]:$$

$$(46)$$

Computing the unconditional expectation over (46) yields  $E[_t] = 0$ . Similarly, postmultiplying (46) by t and t 2 t gives

$$E\begin{bmatrix} t & t \end{bmatrix} = E\begin{bmatrix} a_t & tj/t \end{bmatrix} \quad E\begin{bmatrix} a_t & tj/t \end{bmatrix}$$
$$E\begin{bmatrix} t & t \end{bmatrix} = E\begin{bmatrix} a_t & tj/t \end{bmatrix} \quad E\begin{bmatrix} a_t & tj/t \end{bmatrix}$$

as t / t / t. Again taking the unconditional expectation over the right-hand sides, we have E[t ] = E[t ] = 0 for all t 2 t.

**Su ciency** We demonstrate su ciency by construction. Let  $a_t = [a_t/t]$  and consider the information set  $t_t = S_t [f_s_t g_0]$ , where  $s_t = a_t + t = t$  is a signal that replicates the correlation structure of the expectation we wish to implement. Notice that  $t_t$  inherits recursiveness from  $S_t$ , ensuring consistency with Assumption 2.

From the law of iterated expectations, we have  $E[a_t j s_t] = E[a_t j s_t]$  as  $s_t = t_t$ . Projecting

 $\hat{a}_t$  onto  $s_t$  we obtain

$$E[a_t j s_t] = Cov[a_t; s_t] Var[s_t]^{-1} s_t$$
  
= Cov[s\_t \_\_t; s\_t] Var[s\_t]^{-1} s\_t  
= Var[s\_t] Var[s\_t]^{-1} s\_t  
= s\_t; \qquad (47)

where the second line follows from the denition of  $s_t$  and the third line follows from condition (ii) of the Theorem and the fact that  $s_t = t_t 2 S_t$ . Noting that by construction no other  $t_t 2 S_t$  can improve the forecast about  $a_{t_t}^{29}$  we obtain

$$E[a_t/s_t] = E[a_t/t] = E[a_t/t] + t$$

As the argument above applies to any  $\int_{i,t}^{j} 2T$ , we have constructed exactly the information sets needed to satisfy (45) for all (i; j; t):

<sup>&</sup>lt;sup>29</sup>To see this, note that the forecast error conditional on  $s_t$  is necessarily uncorrelated with any other  $t \ge S_t$ :  $Cov[a_t = Efa_t]s_tg_{t-1}] = Cov[a_t = s_t; t] = Cov[a_t = a_t = cov[a_t = a_t; t] = Cov[a_t = a_t = cov[a_t = a_t; t] = 0$ . Here the rst equality follows from (47); the second one follows per the denition of t; the third one follows, because  $a_t = a_t$  denes the forecast error under full information  $t_t$ , so that any  $t \ge S_t = t_t$  must be orthogonal to it; and the last equality follows from the conditions of the theorem.

# B Online Appendix: Additional Proofs and Results

# B.1 Proof of Lemma 1

The characterization for  $\hat{y}_t$  is immediate. To solve for  $t_t$ , let  $t_t$ 

Equipped with Lemma 2, our proof proceeds in two steps. First, we derive the mappings  $(;) \mathbb{V}_{s}$  and  $(;f) \mathbb{V}_{s}$  in closed form. Second, with this explicit characterization at hand, we complete the proof by constructing processes for and f that for any given (;) satisfy the conditions of Lemma 2.

**Characterization of** s The mapping s is immediate from (37),

 $s(;) = Cov[t; d_t^x]$ 

Using (54) to eliminate  $dy_{i;t+1}$  in (51), we have

(1) 
$$db_{i;t} + (L^{1} 1) (L)_{+ i;t} = {1 (L^{1} 1)B(L)_{+ i;t}}$$
 (56)

where  $[]_+$  sends the negative powers of *L* to zero. Further using (56) to eliminate  $db_{i;t}$  in (55) and applying the *z*-transform, we obtain the following functional equation

$$\begin{pmatrix} 1 & {}^{1}z \\ h & z \end{pmatrix} = \begin{pmatrix} 1 & {}^{1}z \\ h & z \end{pmatrix} = \begin{pmatrix} 1 & {}^{1}z \\ {}^{1}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{1}z \\ {}^{1}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{2}z \\ {}^{1}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{2}z \\ {}^{2}z \\ {}^{2}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{2}z \\ {}^{2}z \\ {}^{2}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{2}z \\ {}^{2}z \\ {}^{2}z \\ {}^{2}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{2}z \\ {}^{2}z \\ {}^{2}z \\ {}^{2}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{2}z \\ {}^{2}z \\ {}^{2}z \\ {}^{2}z \\ {}^{2}z \\ {}^{2}z \end{bmatrix} = \begin{pmatrix} 1 & {}^{2}z \\ {}^{2}z$$

Evaluating (57) at z = 2 (1;1), pins down 0 and (z), from which we obtain the following equilibrium process for d  $y_{i;t}$  dy(L)  $_{i;t}$  and d  $c_{i;t}$  dc(L)  $_{i;t}$ :

$$dy(z) = {\begin{array}{cccc} h & i & h & i \\ 1 & (1 & z)B(z) + & 1 & 1 & (1 & )B() \end{array}} (58)$$

and

Collecting equations, we obtain

$$s(f) = Cov 4 = \frac{2}{i_{i}t_{i}} 4 = \frac{3}{1} = \frac{3}{5} (1 - L)B(L) = \frac{3}{i_{i}t_{i}} 5$$

To begin, substitute (60) to (49), post-multiply both sides by

and apply the z-transform, to obtain the equivalent functional equation

$$\begin{array}{c}
\overset{\ast}{} (z) = \begin{array}{c} \overset{\ast}{1} \begin{array}{c} 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{array} \\ B(z)(1 & z \ {}^{1})B(z \ {}^{1})^{\ell} + \begin{array}{c} 40 & 1 & 0 & 15 \\ 40 & 1 & 0 & 15 \\ 0 & 0 & 1 & 0 \end{array} \\ + B(z)(1 \ {}^{2})B()^{\ell} \begin{array}{c} 40 & 0 & 0 \\ 0 & 0 & 0 \end{array} \\ + B(z)(1 \ {}^{\ell})B()^{\ell} \begin{array}{c} 40 & 0 \\ 0 & 0 \end{array} \\ \end{array}$$

where  $(z) = Zf = {}_{s}Mg_{s=0}$  is the (one-sided) *z*-transform of  $f = {}_{s}Mg_{t}$ , and where *B* parametrizes the joint process ( $=_{i;t}; = f_{i;t}$ ) as in the characterization of above. In particular, let

$$B(L) = \begin{array}{c} 2 & 3 \\ B & (L) \\ 4 & B_a(L) \\ B_z(L) \end{array}$$

where B(z) is a lag-polynomial of size 2 n,  $B_a(z)$  and  $B_z(z)$  are each lag-polynomials of size 1 n, and n is an arbitrary number of innovations. Then (61) can be further rewritten as

$$\tilde{z}_{1}(z) + (z) = (1 \quad z^{-1})B(z)B(z^{-1})^{\ell} + (z) + B(z)B(z^{-1})^{\ell}$$
 (62)

and

$$\tilde{z}_{2}(z) = (1 \quad z^{-1})B(z)B_{a}(z^{-1})^{\ell} + z^{-1}$$
(63)

where  $\sim_1$  and  $\sim_2$  correspond to the rst two and third column of  $\sim$ , respectively, and where

$$(z)$$
  $B(z)$   $(1 )B_{z}()^{\ell}$   $(1 z)$ 

and

Fix N h as the largest non-zero power of z in  $\sim$ . Consider the following parametric structure for B,  $B_{a_1}$  and  $B_z$ :

2 3 2					3
_B (z)	(Z)		1		_
$4B_a(z)5 = 4$	$_{a}(Z)$	(1	Z)	1	2 a;05
$B_z(z)$	0	<i>z;</i> 0	+	Z;	-1 <i>Z</i>

with

h  

$$(z) = \frac{1}{1} + z$$
 .)+2953411 0 Td [()) - 841((1)]TJ

$${}_{0} \qquad \begin{pmatrix} h \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ z \end{pmatrix} {}_{z,0}^{\ell} + {}_{z,1}^{\ell} {}_{z,0}^{\ell} z$$

Notice that (i) the left-hand side, (z), is exogenously determined by the aggregate economy that we are trying to implement, and (ii) we have  $_0$  as a degree of freedom to induce an arbitrary unconditional covariance on the right-hand side. Writing out the right-hand side in the time-domain, we have

$${}_{0} = {}_{0} {}_{j1}^{\ell} + \frac{2}{1 - 2} + \underbrace{\times}_{j=1}^{2} {}_{jj}^{\ell} {}_{jj}(l + ) + \underbrace{\times}_{j=1}^{2} {}_{j=1}^{j} {}_{jj} {}_{jj} {}_{jj} {}_{j} {}_{j}$$

where the rst equality exploits that by Theorem 1  $\frac{p;h}{i;t}$ ?  $\frac{h}{i;t-s}$  and thus  $\frac{p;h}{i;t}$ ?  $(n_{i;t-s};c_{i;t-s})$  for all s = 0.

Similarly, substituting for  $w_{i;t}$  using the rm's labor demand and taking rst di erences, orthogonality of the rm wedge with respect to  $dw_{i;t}$  requires

$$\operatorname{Cov}[\begin{array}{c} p; f\\ i; t \end{array}; da_{i;t} + dp_{i;t} + d \begin{array}{c} p; f\\ i; t \end{array}] = \operatorname{Cov}[\begin{array}{c} p; h\\ i; t \end{array}; d \begin{array}{c} p; f\\ i; t \end{array}] = 0:$$
(67)

Here the rst equality follows as  $p_{i,t}^{p,f} ? = \frac{f}{i;t=0}$  implies  $p_{i,t}^{p,f} ? = n_{i;t=0}$  for all s = 0 and, hence,  $p_{i,t}^{p,f} ? (dy_{i;t} = dn_{i;t} + dp_{i;t})$  under the conditions of the proposition.

Subtracting (66) from (67), we have

$$\operatorname{Cov}\begin{bmatrix}p & p \\ i:t & t\end{bmatrix} = 0$$

or

 $(1 \quad \operatorname{Corr}[\hat{y}_{t}; \hat{y}_{t-1}]) \quad {}^{1}\operatorname{Var}[\hat{y}_{t}] \quad \operatorname{Cov}[\hat{y}_{t}; t] = 1 \quad \operatorname{Corr}[\begin{array}{c} p \\ i_{t}t \\ i_{t} \end{array}] \quad \operatorname{Var}[\begin{array}{c} p \\ i_{t} \\ i_{t} \end{array}] \quad \operatorname{Var}$ 

which implies the bound given in the statement of the proposition.

### 

# C Online Appendix: Estimation of Unrestricted Wedge Process

Here we describe the methodology for estimating the unrestricted wedges  $_t$  used in Section 5.

#### C.1 Description of Methodology

We model the unrestricted wedges as a MA(14) process, which loads on two intrinsic innovations, represented by the 2 -1 vector  $u_t$ , in addition to the productivity shock  $t_t$ ,

$$t = (L) t + u(L) U_t$$

where (L) and  $_{u}(L)$  are square-summable lag polynomials in non-negative powers of L, and  $_{t}$  and  $u_{t}$  are orthogonal white noise. W.I.o.g., we normalize  $Var[u_{t}] = I_{2}$ , leaving us to estimate  $_{ma}$  ( $; _{u};$ ). For this purpose, we use the generalized method of moments (GMM) to minimize the distance between the model's covariance structure and U.S. data on real per-capita output, in ation, nominal interest rates, and per-capita hours.<sup>31</sup> Let

$$\tilde{q}_{t} = vechf \operatorname{Var}[(q_{t}^{\operatorname{data}}, \ldots, q_{t-k}^{\operatorname{data}})]g_{t}$$

denote the empirical auto-covariance matrix of frequency- Itered quarterly US data for q  $(y_t; t; i_t; n_t)$ . We target auto-covariances between zero and k = 8 quarters. For the Itering, we use the Baxter and King (1999) approximate high-pass Iter with a truncation horizon of 32 quarters, which we denote by  $q_t = BK_{32}(q_t)$ .<sup>32</sup>

To conserve on the 91 parameters that characterize  $_{ma}$ , we make two observations, documented in Figure 4 below. First,  $\sim_{T}$  is well-described by a VAR(1) process for  $_{t}$ . Second, a MA(14) truncation of the VAR(1) process that best replicates  $\sim_{T}$  is almost indistinguishable (in terms of second moments) from the VAR(1) process itself. Accordingly, we construct  $_{ma}$ by rst estimating  $_{t}$  as a VAR(1) that is driven by  $u_{t}$  and  $_{t}$ , and then constructing  $^{n}_{ma}$  as the MA(14) truncation of the estimated process.<sup>33</sup>

Let  $_{ar}$  denote the 10 parameters characterizing the VAR(1) and  $\$ . Then the estimator is given by

$$^{n}_{ar} = \operatorname{argmin}_{ar} (^{T}_{T} (^{ar}))^{\ell} W^{-1} (^{T}_{T} (^{ar})); \qquad (68)$$

where  $\sim$  ( $_{ar}$ ) is the model analogue to  $\sim_{T}$  and W is a diagonal matrix with the bootstrapped variances of  $\sim_{T}$  along the main diagonal. To avoid the issues detailed in Gorodnichenko and Ng (2010), our model analogue  $\sim$  ( $_{ar}$ ) is computed after applying the same Itering procedure to the model that we have applied to the data.

A nal challenge for estimating the model is that Itering the model can be computational expensive. We address this issue by proving the following equivalence results (see Appendix C.3 for proof).

Lemma 3. Estimator (68) is equivalent to

$$^{\text{ar}} = \underset{ar}{\operatorname{argmin}} (_{T} (_{ar}))^{\ell} \mathcal{W}^{-1} (_{T} (_{ar})); \qquad (69)$$

where  $vechfVar[(ds_t; :::; ds_t \kappa)]g$  and W ( ${}^{\emptyset}W^{-1}$ )  ${}^{1}$  for K = k + 2. The trans-

<sup>&</sup>lt;sup>31</sup>Data range from 1960Q1 to 2012Q4. Real output is given by nominal output divided by the GDP de ator. In ation is de ned as the log-di erence in the GDP de ator. Interest rates are given by the Federal Funds E ective rate. Hours are given by hours worked in the non-farm sector. Variables are put in per-capita terms using the non-institutional population over age 16.

<sup>&</sup>lt;sup>32</sup>The Baxter and King (1999) Iter requires speci cation of a lag-length for the approximation. We set to their recommended value of 12.

<sup>&</sup>lt;sup>33</sup>Our estimator penalizes excessively persistent dynamics beyond the usual business cycle horizon by imposing a numerical penalty on impulse responses beyond 32 quarters.

dence intervals (depicted by the shaded areas). The solid blue and red lines show the corresponding moments for the estimated model for the VAR(1) and MA(14) truncation of the wedges, respectively. Each row *i* and column *j* in the table of plots shows the covariances between  $q_t^i$  and  $q_{t-k}^j$  with lags  $k \ge f_{0;1;\ldots;8g}$  depicted on the horizontal axis. Despite the parametric restriction on t and  $a_t$  and the fact that we have less shocks than data series, the unrestricted-wedge model does a very good job at capturing the auto-covariance structure of the four time series. In addition, there is no notable di erence between the VAR(1) and MA(14) truncation of t.

### C.3 Proof of Lemma 3

where

$$= P_{0} \begin{pmatrix} 2 & 3 \\ 8L_{0} & BL_{0} \\ \vdots & 5 \\ BL_{k} & BL_{0} \end{pmatrix}$$
(74)

with B and  $L_j$  as in (72) and (73). Substitution in (70) yields (71).

# D Online Appendix: Comparative Statics With Countercyclical In ation

In analogue to Figure 2, we explore comparative statics with respect to the parametrization of the micro-shocks, but for the case where in ation is countercyclical with y = ...3. The results, shown in Figure 5, display the same qualitative pattern as for the procyclical case explored in the main text. While the maximal volatility is higher, we again see a clear positive relationship between  $y^{max}$  and the volatilities of the micro shocks. As before, the impact of idiosyncratic demands shocks is most relevant, paralleling their key role in the procyclical case.

Here we do not include the cases without demand uncertainty  $(p_{i;t} 2 \stackrel{f}{}_{i;t})$ , because in line with our discussion in the main text, in these cases in ation is necessarily procyclical (see Appendix B.3 for a formal proof). Intuitively, this re ects again the discrepancy in propagation underlying the pro- and countercyclical in ation cases: While procyclical in ation is tied to nominal misperception and expectation errors about aggregate prices, countercylical in ation is tied to expectation errors regarding local demand, and thus is impossible to implement when  $p_{i;t}$  is observed by rms. (See also the explanations given in the context of Figure 1.)

